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## SMS / text commands

Text commands can be issued by SMS, serial port (DIAG) or IP (App/Web/Perl). This overview does not cover all commands and details, please read the user guides for more info.

### Notes:

- Disable automatic spelling correction.
- Use exactly one blank to separate arguments.
- Do not separate the „?“ from a query command (e.g. „SERVER?“).
- Case is irrelevant on commands (PASS = pass) but may be relevant on arguments (i.e. login, password, ...).
- Wait for acknowledgement of each command sent before sending the next. If you get no reply, check spelling and try again.

## OVMS configuration

### Basic setup

| Command  | Function  |
|--|---|
| REGISTER <i>password</i>                       | Register sending mobile phone as primary user (only SMS). Initial password is "OVMS".                   |
| PASS <i>newpassword</i>                        | Change REGISTER password (only from registered phone)   |
| MODULE <i>vehicleid units channels cartype</i> | Set vehicle id (= server login), units ("M" / "K"), notification channels ("SMSIP") and car type ("RT") |

| Command | Function  |
|---------|---|
|         | <i>Note: vehicle password set by SERVER command</i> |

## IP setup (GPRS)

| Command  | Function   |
|--|--|
| GPRS <i>apn apnuser apnpassword</i>                | Set APN config   |
| SERVER <i>address vehiclepassword paranoidmode</i> | Configure server connection; paranoidmode "-" or "P" (end-to-end encryption = server cannot decode data, no logs etc.)<br><i>Note: vehicle login set by MODULE command</i> |

## Troubleshooting

| Command   | Function  |
|-----------|---|
| VERSION   | Query firmware version  |
| DIAG      | Show LED and communication status (see "Network-State-Machine.pdf") |
| MODULE?   | Query module config   |
| GPRS?     | Query APN config & GPRS status                                      |
| SERVER?   | Query server config & status  |
| PARAMS?   | Query all parameters  |
| FEATURES? | Query all features  |
| RESET     | Restart the module  |

## Twizy configuration

### Range & charge alerts

| Command               | Function   |
|-----------------------|--|
| RANGE <i>maxrange</i> | Set your max range (in user units) at 100% SOC & 20 °C           |
| CA <i>range</i>       | Set charge alert for sufficient range (in user units)            |
| CA <i>soc%</i>        | Set charge alert for sufficient SOC (note: "%" must be added)    |
| CA <i>range soc%</i>  | Set charge alert for sufficient range (in user units) and/or SOC |
| CA                    | Clear charge alerts  |

### Feature map

| Command                               | Function  |
|---------------------------------------|---|
| FEATURE 1 <i>kickdownthreshold</i>    | Kickdown sensitivity (default 35, lower value = faster activation)  |
| FEATURE 2 <i>kickdowncompensation</i> | Kickdown pedal compensation point (default 120)   |
| FEATURE 8 <i>gpsstreaming</i>         | <ul style="list-style-type: none"><li>• 0 = no location streaming, GPS log entry once per minute</li><li>• 1 = location streaming every 2 seconds, GPS log entry per minute</li><li>• 2 = no location streaming, GPS logging every 5 seconds</li><li>• 3 = location streaming every 2 seconds, GPS logging every 5 seconds</li></ul> <p>If you don't need App streaming, mode 0 is perfect for normal resolution tracks, and mode 2 is perfect for high resolution track logging.</p> |
| FEATURE 9 <i>minsoc</i>               | Low SOC warning threshold (default: 0)  |
| FEATURE 10 <i>sufficientsoc</i>       | Charge notification by SOC (in %)   |
| FEATURE 11 <i>sufficientrange</i>     | Charge notification by range (in user unit)   |
| FEATURE 12 <i>maxrange</i>            | Range (in user units) at 100% SOC & 20 °C   |
| FEATURE 13 <i>batterycapacity</i>     | Running average (last 10 charges) capacity value  |

| Command                              | Function   |
|--------------------------------------|--|
|                                      | (percentage), 0 = clear<br><i>Note: shown as integer, but stored as float</i>  |
| FEATURE 14 <i>communicationflags</i> | Communication control: add... <ul style="list-style-type: none"><li>• 2 = suppress "Access Denied" SMS</li><li>• 4 = suppress all outbound SMS</li><li>• 8 = suppress vehicle alerts</li><li>• 16 = suppress vehicle info notifies</li><li>• 32 = suppress times in SMS responses</li><li>• 64 = send charge start notifications</li></ul> |
| FEATURE 15 <i>canbusflags</i>        | CAN bus access control: add... <ul style="list-style-type: none"><li>• 1 = enable CAN write access</li><li>• 2 = disable emergency CFG RESET</li><li>• 4 = disable kickdown</li><li>• 8 = disable auto power adjustment</li></ul>  |

## Twizy status

| Command | Function  |
|---------|---|
| STAT?   | Query battery state of charge (SOC) and capacity, range, charge status, odometer                              |
| GPS?    | Query GPS position  |
| TEMPS?  | Query temperatures  |
| CA?     | Query charge alert setup (features 10+11), charge status & charge time estimations for alerts and full charge |
| RANGE?  | Query max range setting in user units (feature 12)  |
| POWER   | Show power efficiency (trip report)   |
| POWER T | Show power usage sums   |
| BATT    | Show battery alert and watch status   |
| BATT V  | Show battery voltage levels   |
| BATT VD | Show battery cell voltage deviations  |
| BATT T  | Show battery temperatures   |
| BATT TD | Show battery module temperature deviations  |

## SEVCON tuning

### Notes:

- You need to enable CAN write access (FEATURE 15 1).
- Some commands use the STOP mode, the Twizy may signal that and beep, that's normal.
- If stuck in STOP mode, restart Twizy without entering GO, wait for 10-15 seconds.
- 3 successive CAN bus errors (for example pushing button D/N/R before GO) will cause an emergency CFG RESET. If your Twizy has a component problem or is used by inexperienced drivers, you may want to disable this by FEATURE 15 3.

## Macro settings

Macro commands automate the tuning process and can easily be reset.

| Command  | Function  |
|--|---|
| CFG SPEED <i>max_kph warn_kph</i>  | Set speed limit and warn level.<br>max_kph: 6..111, default 80 (T45: 45)<br>warn_kph: 6..111, default 89 (T45: 56)<br><i>Note: needs ON before GO</i>   |
| CFG POWER <i>torque power_low power_high current</i>   | Set torque, power and current levels. <u>With current</u> :<br>torque: 10..254 (%), default 100<br>power_low: 10..254 (%), default 100<br>power_high: 10..254 (%), default 100<br>current: 10..123 (%), default none<br><i>Note: needs ON before GO</i>   |
| CFG DRIVE <i>powerlevel autopower_ref autopower_min kickdown_threshold kickdown_compensation</i> | Set drive power level, optional auto power adjustment and kickdown parameters.<br>powerlevel: 10..100 (%), default 100<br>autopower_ref: 0..250 (100 W), default 0/-1=off<br>autopower_min: 0..100 (%), default 0/-1=none<br>kickdown_threshold: 0..250, default 35 (= Feature #1)<br>kickdown_compensation: 0..250, default 120 (= Feature #2) |
| CFG RECUP <i>neutral brake autopower_ref autopower_min</i>                                       | Set recuperation power levels, optional auto power adjustment.<br>neutral: 0..100 (%), default 18 (T45: 21)<br>brake: 0..100 (%), default = neutral%<br>autopower_ref: 0..250 (100 W), default 0/-1=off<br>autopower_min: 0..100 (%), default 0/-1=none   |
| CFG RAMPS <i>start accel decel neutral brake</i>   | Set rates of torque demand changes (higher means faster).<br>start: 1..250 (%), default 40 (T45: 30)<br>accel: 1..100 (%), default 25 (T45: 21)<br>decel: 0..100 (%), default 20<br>neutral: 0..100 (%), default 40<br>brake: 0..100 (%), default 40  |
| CFG RAMPL <i>accel decel</i>   | Set rpm change limits for ramps.  |

| Command  | Function  |
|--|---|
|  | accel: 1..100 (%), default 30 = 6000 rpm/s<br>decel: 0..100 (%), default 30 = 6000 rpm/s  |
| CFG SMOOTH <i>level</i>                                      | Set smoothing level.<br>level: 0..100 (%), default 70   |
| CFG TSMAP <i>map trq1@spd1 trq2@spd2 trq3@spd3 trq4@spd4</i> | Change torque/speed maps.<br>map: D = Drive, N = Neutral braking, B = Footbraking<br>trq1..4: torque 0..100 (%)<br>spd1..4: speed 0..120 (kph)<br>Defaults:<br>D: 100@33 100@39 100@50 100@66<br>N,B: 100@33 80@39 50@50 20@66<br><i>Note: needs ON before GO</i> |
| CFG RESET  | Reset all macro settings to their default values.<br><i>Note: needs ON before GO (else partial)</i>   |
| CFG CLEAR  | Clear the SEVCON fault & min/max logs.  |

## Profile management

A profile stores a combination of macro settings and can be loaded by command (or by button if using a SimpleConsole). The OVMS can store 3 custom profiles in EEPROM plus the current SEVCON working set in RAM.

| Command                        | Function   |
|--------------------------------|--|
| CFG INFO                       | Output currently active profile slot# and working set parameters for these commands:<br>SPEED, POWER, DRIVE, RECUP, RAMPS, SMOOTH  |
| CFG SAVE <i>slot</i>           | Save the current working set into an EEPROM slot.<br>slot: 1..3  |
| CFG LOAD <i>slot</i>           | Load a profile slot into the current working set.<br>slot: 0..3, 0=factory default config, 1..3=custom profile   |
| CFG RESET <i>slot</i>          | Reset a profile slot to the default values.<br>slot: 1..3: reset EEPROM profile directly<br>...else: reset working set   |
| CFG GET <i>slot</i>            | Get (download) a complete profile base64 encoded.<br>slot: 1..3: get EEPROM profile directly<br>...else: get working set   |
| CFG SET <i>slot base64data</i> | Set (upload) a complete profile from a base64 encoded string (counterpart to CFG GET).<br>slot: 1..3: set EEPROM profile directly, no SEVCON access<br>...else: set working set & try to apply changes to SEVCON |

| Command | Function   |
|---------|--|
|         | base64data: encoded profile from CFG GET or cfgconv<br>...omit/empty = RESET profile |

Base64 web utilities:

- <http://dexters-web.de/cfgconv>
- <http://dexters-web.de/cfgedit>

## Temporary speed limits

| Command         | Function  |
|-----------------|---|
| LOCK <i>kph</i> | Immediately and persistently limit the maximum speed. If kph is lower than the default reverse speed (~10 kph), the reverse speed will also be limited.                     |
| UNLOCK          | Clear the speed lock and reset maximum speed to the current profile configuration. If locked by valet mode, the valet trip length will be extended by 1 km but stay active. |
| VALET <i>km</i> | Activate valet mode and set the allowed trip length in km. Speed will be restricted to 6 kph when exceeding trip length. Default trip length = 1 km.                        |
| UNVALET         | Clear valet mode trip length restriction. If a speed lock is currently active, also clears the lock.  |

## Low level access

These commands provide direct access to the SEVCON configuration objects (SDO = service data object, see CANopen standard).

*Att: no backup, no easy reset, note values or save logs!*

| Command  | Function   |
|--|--|
| CFG PRE  | Enter pre-operational state ("STOP", needed for some SDOs).<br><i>Note: only necessary for few SDOs; see FAQ</i>               |
| CFG OP   | Enter operational state. As an alternative, just switch the Twizy off for 2-3 seconds, then on again & wait for 10-15 seconds. |
| CFG READ <i>index_hex</i><br><i>subindex_hex</i> | Read CANopen SDO object numerical contents (displays hexadecimal and decimal value).<br>index_hex: SDO address (hexadecimal)   |

| Command   | Function  |
|---|---|
|   | subindex_hex: SDO field (hexadecimal)   |
| CFG READS <i>index_hex</i><br><i>subindex_hex</i>                   | Read CANOpen SDO object string contents.<br>index_hex: SDO address (hexadecimal)<br>subindex_hex: SDO field (hexadecimal)   |
| CFG WRITE <i>index_hex</i><br><i>subindex_hex</i> <i>value_dec</i>  | Write CANOpen SDO object.<br>index_hex: SDO address (hexadecimal)<br>subindex_hex: SDO field (hexadecimal)<br>value_dec: new value (decimal)                                  |
| CFG WRITE0 <i>index_hex</i><br><i>subindex_hex</i> <i>value_dec</i> | Write-only CANOpen SDO object (i.e. no READ before write).<br>index_hex: SDO address (hexadecimal)<br>subindex_hex: SDO field (hexadecimal)<br>value_dec: new value (decimal) |

## Low level examples

| Command                | Function   |
|------------------------|--|
| CFG READS 1008 0       | Read SEVCON firmware name (string)   |
| CFG READS 1009 0       | Read SEVCON hardware version (string)  |
| CFG READS 100A 0       | Read SEVCON software version (string)  |
| CFG READ 1018 3        | Read SEVCON dictionary version (hex)   |
| CFG WRITE 4623 03 0    | Disable battery / BMS power protection (power limiter)<br><i>ATT: voids warranty on rented battery!</i><br><i>Activate auto power on DRIVE &amp; RECUP to protect battery!</i> |
| CFG WRITE 3813 12 5000 | Disable SEVCON low SOC power cutback<br><i>Note: BMS protection still applies unless disabled, else use auto power on DRIVE to protect battery!</i>                            |
| CFG READ 2870 06       | Read current BMS discharge (=drive) power limit:<br>$power_{kW} = \frac{value_{dec}}{256}$   |
| CFG READ 2870 07       | Read current BMS charge (=recup) power limit:<br>$power_{kW} = \frac{65536 - value_{dec}}{256}$  |

See "Twizy-SDO-List.pdf" for a selection of relevant SDOs or SEVCON DVT master dictionary spreadsheet for complete SDO list & documentation.